Cruz Chavez

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Vehicle Simulator Visionary Listings/Future Funding Ideation

* Implementation of multiple running vehicles on one machine. (Will require further integration to supply-side server)
* Fleet of vehicles of which to modify for automated travel.
* Hardware matching the specifications of WeGo Vehicle Simulator platform for deployable vehicles in the visionary future.
* Sensory components for implementation on tangible vehicles and fleet objects. Examples include but are not limited to:
  + Motion detection sensors for automated defensive handling on roads.
  + Built in cameras for use in documentation and on-sight use of vehicles.
  + Speedometer technology for use in vehicle control.
  + Fuel capacity for gasoline or electric power as well as a meter for it.
  + Sensors to indicate tire pressure.
  + Oil indicators for change in fuel efficiency.
  + Heat sensory for temperature sensitive components and elements.
  + All purpose handling based on climate and conditions.
* Specific vehicle components matching WeGo Taas platforms and conditions (such as refrigeration capabilities for Ice Cream vehicles, or built in oven capabilities for Pizza vehicles).